

Temposonics®

Magnetostrictive Linear Position Sensors

RT4 SSI Data Sheet

- Redundant SSI output
- High temperature rod
- IP68 ingress protection



MEASURING TECHNOLOGY

For position measurement, the absolute, linear Temposonics® position sensors make use of the properties offered by the specially designed magnetostrictive waveguide. Inside the sensor a torsional strain pulse is induced in the waveguide by momentary interaction of two magnetic fields. The interaction between these two magnetic fields produces a strain pulse, which is detected by the electronics at the head of the sensor. One field is produced by a moving position magnet, which travels along the sensor rod with the waveguide inside. The other field is generated by a current pulse applied to the waveguide. The position of the moving magnet is determined precisely by measuring the time elapsed between the application of the current pulse and the arrival of the strain pulse at the sensor electronics housing. The result is a reliable position measurement with high accuracy and repeatability.

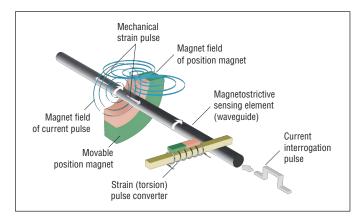


Fig. 1: Time-based magnetostrictive position sensing principle

RT4 SENSOR

Robust, non-contact and wear-free, the Temposonics® linear position sensors provide best durability and accurate position measurement solutions in harsh industrial environments. Designed for demanding applications that require redundancy and detached electronics due to high temperature or high reliability requirements. The position measurement accuracy is tightly controlled by the quality of the waveguide which is manufactured by MTS Sensors. The position magnet is mounted on the moving machine part and travels contactlessly over the sensor rod with the built-in waveguide.

RT4 sensor specifications:

- Redundant R-series detached electronics for enhanced safety applications
- High temperature rod (up to +100 °C)
- Detached electronics up to 600 mm from sensor rod
- IP68 ingress protection
- Linear, absolute measurement
- Non-contact sensing technology
- Linearity deviation less than 0.02 %
- Direct 24/25/26 bit SSI output, gray/binary formats
- LEDs for sensor status and diagnostics

Applications:

- Steel, wood, power generation, fluid power



Fig. 2: Typical application: metal processing

TECHNICAL DATA

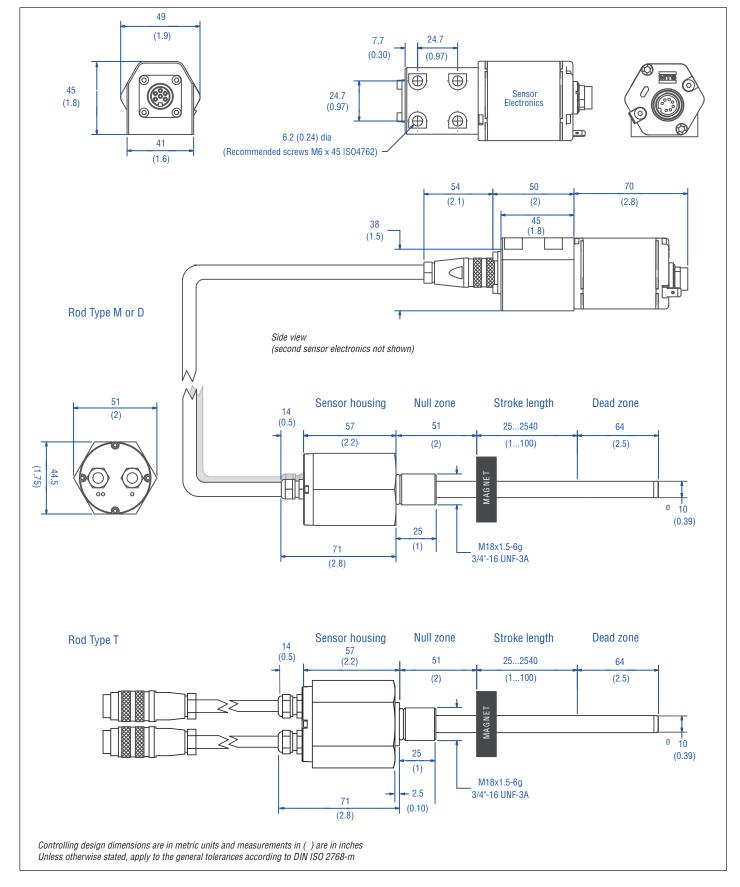
Output				
Interface	SSI (Synchronous Serial Interface) - differential signal in SSI standard (RS 422)			
Data protocol	Binary or Gray, optional: parity and error bit			
Data length	24, 25, or 26 bit			
Data transmission rate	70 kBaud*1 MBaud, depending on cable length: Length			
Measured value	Position			
Measurement parameters				
Resolution	1 μm, 2 μm, 5 μm, 10 μm, 20 μm, 50 μm, 100 μm			
Cycle times	Stroke length 300 750 1000 2000 mm Measurement rate 3.7 3.0 2.3 1.2 kHz			
Linearity ¹	< ±0.02 % F.S. (minimum ±50 μm)			
Repeatability	0.001 % F.S. (minimum ±2.5 μm)			
Operating conditions				
Operating temperature	Sensor electronics: -40 °C (-40 °F) to +75 °C (+167 °F) Sensor rod with interconnection cable: -40 °C (-40 °F) to +100 °C (+212 °F)			
Humidity	90% humidity, no condensation			
Ingress protection	Sensor electronics: IP67 (with professionally mounted housing and connectors) Sensor housing with interconnection cable: IP68			
Shock test	100 g (single hit) / IEC standard 60068-2-27			
Vibration test	10 g / 10 to 2000 Hz, IEC standard 60068-2-6 (resonance frequencies excluded)			
EMC test ²	Electromagnetic emission: IEC/EN 50081-1 Electromagnetic susceptibility: IEC/EN 50082-2 IEC/EN 61000-4-2/3/4/6, level 3/4 criterium A			
Magnet movement velocity ¹	Any			
Design/Material				
Sensor electronics	Aluminum housing with diagnostic LED display. (LEDs located beside connector/cable exit)			
Sensor housing	Stainless steel 1.4305, AISI 304L			
Stroke length	252540 mm (1100 in.)			
Operating pressure	350 bar static, 690 bar peak (5000 psi, 10,000 psi peak)			
Mechanical mounting				
Mounting position	Any orientation			
Mounting instruction	Please consult the technical drawings			
Electrical connection				
Connection type	7 pin connector M16 or integral cable			
Operating voltage	+24 VDC (-15% / +20 %)			
Ripple	≤ 0.28 Vpp			
Current consumption	100 mA per sensor electronics			
Dielectric strength	500 VDC (DC ground to machine ground)			
Polarity protection	up to -30 VDC			
Overvoltage protection	up to 36 VDC			

 $^{^{*}\!\!/}$ with standard monoflop of 16 μs

^{1/} With position magnet # 201 542-2

^{2/} Sensor rod and interconnection cable are mounted in a metal housing (e.g. in a cylinder).

TECHNICAL DRAWINGS (Detached electronics with side cable entry)



CONNECTOR WIRING

M16 connector

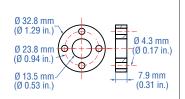
D70	Pin	Function
000	1	Data (–)
	2	Data (+)
	3	Clock (+)
	4	Clock (-)
	5	+24 VDC (-15 / +20 %)
	6	DC Ground (0 V)
	7	n.c.

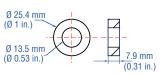
Cable outlet

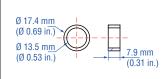
Cable	Function
GY	Data (-)
PK	Data (+)
YE	Clock (+)
GN	Clock (-)
BN	+24 VDC (-15 / +20 %)
WH	DC Ground (0 V)

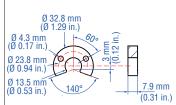
FREQUENTLY ORDERED ACCESSORIES – Additional options available in our Accessories Catalog 3550929

Position magnets









Standard ring magnet 0032.8 Part no. 201 542-2

Material: PA ferrite GF20
Weight: ca. 14 g
Operating temperature:
-40...+105 °C (-40...+221 °F)
Surface pressure: max. 40 N/mm²
Fastening torque for M4 screws:
max. 1 Nm

Ring magnet OD25.4 Part no. 400 533

Material: PA ferrite Weight: ca. 10 g Operating temperature: -40...+105 °C (-40...+221 °F) Surface pressure: max. 40 N/mm²

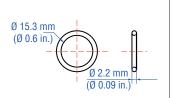
Ring magnet 0D17.4 Part no. 401 032

Material: PA neobind Weight: ca. 5 g Operating temperature: -40...+105 °C (-40...+221 °F) Surface pressure: max. 20 N/mm²

U-magnet 0D33 Part no. 251 416-2

Material: PA ferrite GF20 Weight: ca. 11 g Operating temperature: -40...+105 °C (-40...+221 °F) Surface pressure: max. 40 N/mm² Fastening torque for M4 screws: max. 1 Nm

Optional installation hardware





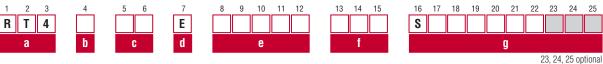
0-ring Part no. 401 133

Material: Fluoroelastomer 75 ± 5 durometer Application: M-style housings

0-ring Part no. 560 315

Material: Fluoroelastomer 75 ± 5 durometer Application: T and D -style housings Data Sheet

ORDER CODE



Sensor model		
T 4 Rod version		
Sensor rod style		
Flat faced Metric threaded flange, M18x1.5		
Flat faced US customary threaded flange, 3/4"-16		
Raised face US customary threaded flange, 3/4"-16		
Sensor rod interconnection cable		
1 250 mm (9.8 in.) Santoprene cable, hanging connector		
2 400 mm (15.7 in.) Santoprene cable, hanging connector		
3 600 mm (23.6 in.) Santoprene cable, hanging connector		
Electronics housing style		
Side cable electronics connection		
Stroke length		
X X M for mm (00252540 mm in 5 mm increments)		
X X X U for inches (001.0100.0 in. in 0.1 in. increments)		
Connection type		
gral connector		

E Stroke length X X X M for mm (0025...2540 mm in 5 mm increments) X X X X U for inches (001.0...100.0 in. in 0.1 in. increments) f Connection type Integral connector D 7 0 7pin M16 connector Integral Cables (box No. 13, 14, 15) P Integral high-performance cable, orange jacket with pigtail termination R Integral cable, PVC jacket, pigtail termination, standard F Integral cable, black polyurethane jacket with pigtail termination Cable length Encode in feet if using US customary stroke length Encode in meters if using metric stroke length Encode in meters if using metric stroke length Encode in meters if using metric stroke length S (03) to 98 (98) ft. or 1 (01) to 30 (30) meters.

Operating voltage

Without selection input voltage, 24 VDC

g | Output

S(17)(18)(19)(20)(21)(22)(23)(24)(25) = Synchronous Serial Interface

Data length (box no. 17)

- 1 25 bits
- **2** 24 bits
- **3** 26 bits

g Output (continued)

S(17)(18)(19)(20)(21)(22)(23)(24)(25) = Synchronous Serial Interface

Format (box no. 18)

- **B** Binary
- **G** Gray

Resolution (box no. 19)

- **1** 0.005 mm
- **2** 0.01 mm
- **3** 0.05 mm
- **4** 0.1 mm
- 0.1 11111
- **5** 0.02 mm
- **6** 0.002 mm
- 8 0.001 mm

Filtering performance (box no. 20)

- 8 Noise reduction filter (8 values)
- G Noise reduction filter (8 values) + error delay 10 cycles

Signal options (box no. 21 and 22)

- **0 0** Measuring direction forward
- **0 1** Measuring direction reverse
- 0 2 Measuring direction forward, synchronized measurement
- Measuring direction forward, Bit 25 = Alarm,
 Bit 26 = Parity even
- 9 9 Advanced Signal Options (Use next fields 23, 24, 25)

Measurement contents (box no. 23)

1 Position

Direction and Sync mode (box no. 24)

- 1 Forward async
- 2 Forward sync1
- 5 Reverse async
- 6 Reverse sync1

Communication Diagnostics (box no. 25)

- No further option
- 2 Additional alarm bit + parity even bit

DELIVERY



Sensor, O-ring

Accessories have to be ordered separately.

Operation manuals & software are available at:

www.mtssensors.com

NOTES	



UNITED STATES 3001 Sheldon Drive

Temposonics, LLC Cary, N.C. 27513

Americas & APAC Region Phone: +1 919 677-0100

E-mail: info.us@temposonics.com

GERMANY Auf dem Schüffel 9 Temposonics 58513 Lüdenscheid GmbH & Co. KG Phone: +49 2351 9587-0

EMEA Region & India E-mail: info.de@temposonics.com

ITALY Phone: +39 030 988 3819 Branch Office E-mail: info.it@temposonics.com

FRANCE Phone: +33 6 14 060 728

Branch Office E-mail: info.fr@temposonics.com

UK Phone: +44 79 21 83 05 86

Branch Office E-mail: info.uk@temposonics.com

SCANDINAVIA Phone: +46 70 29 91 281

Branch Office E-mail: info.sca@temposonics.com

CHINA Phone: +86 21 2415 1000 / 2415 1001

Branch Office E-mail: info.cn@temposonics.com

JAPAN Phone: +81 3 6416 1063

Branch Office E-mail: info.jp@temposonics.com

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